

Relating Nominal and Higher-order Abstract Syntax Specifications

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Relating the nominal and HOAS worlds

Many approaches to formalizing systems with binding structure

Nominal: names, name-abstraction, freshness, \mathbb{N} -quantifier

HOAS: λ -terms, raising, ∇ -quantifier

Some convergence: Nominal vs higher-order pattern unification
[Cheney 2005, Levy and Villaret 2008]

Difficulties: α Prolog vs λ Prolog

Current work: a translation from α Prolog to \mathcal{G}^-
and from λ Prolog to \mathcal{G}^-

α Prolog example

Encoding of λ -terms

$$\lambda x. \lambda y. x y \rightsquigarrow \text{lam}(\langle a \rangle \text{lam}(\langle b \rangle \text{app}(\text{var}(a), \text{var}(b))))$$

Type checking for λ -terms

$$tc(G, \text{var}(X), A) :- \text{lookup}(X, A, G)$$

$$tc(G, \text{app}(M, N), B) :- \exists A. tc(G, M, \text{arr}(A, B)) \wedge tc(G, N, A)$$

$$tc(G, \text{lam}(\langle x \rangle E), \text{arr}(A, B)) :- x \# G \wedge tc(\text{bind}(x, A, G), E, B)$$

$$\forall x. \forall G. \forall E. \forall A. \forall B.$$

$$tc(G, \text{lam}(\langle x \rangle E), \text{arr}(A, B)) :-$$

$$x \# G \wedge tc(\text{bind}(x, A, G), E, B)$$

α Prolog basics

Syntax

$$t, u ::= a \mid X \mid f(\vec{t}) \mid (a b) \cdot t \mid \langle a \rangle t$$
$$G ::= \top \mid p(\vec{t}) \mid a \# t \mid t \approx u \mid G \wedge G' \mid G \vee G' \mid \exists X.G \mid \forall a.G$$
$$D ::= \forall \vec{a} . \forall \vec{X} . [p(\vec{t}) :- G]$$

Notions

Swapping: $(a b) \cdot (\langle a \rangle b) = \langle b \rangle a$

Freshness: $a \# \langle a \rangle t$

α -Equivalence: $\langle a \rangle a \approx \langle b \rangle b$

Variable capture: $\forall a . \exists X . \langle a \rangle X \approx \langle b \rangle b$ has solution $X \mapsto a$

α Prolog rules

$$\frac{}{\Delta \Longrightarrow \top} \text{ TRUE} \quad \frac{\models a \# t}{\Delta \Longrightarrow a \# t} \text{ FRESH} \quad \frac{\models t \approx u}{\Delta \Longrightarrow t \approx u} \text{ EQUAL}$$

$$\frac{\Delta \Longrightarrow G_1 \quad \Delta \Longrightarrow G_2}{\Delta \Longrightarrow G_1 \wedge G_2} \text{ AND} \quad \frac{\Delta \Longrightarrow G_i}{\Delta \Longrightarrow G_1 \vee G_2} \text{ OR}$$

$$\frac{\Delta \Longrightarrow G[t/X]}{\Delta \Longrightarrow \exists X.G} \text{ EXISTS} \quad \frac{\Delta \Longrightarrow G}{\Delta \Longrightarrow \forall a.G} \text{ NEW}$$

$$\frac{\Delta \Longrightarrow \pi.(G\theta)}{\Delta \Longrightarrow p(\vec{t})} \text{ BACKCHAIN}$$

Where $\forall \vec{a}.\forall \vec{X}.[p(\vec{u}) :- G] \in \Delta$ and π is a permutation and θ is a substitution for \vec{X} such that $\vec{t} \approx \pi.(\vec{u}\theta)$.

\mathcal{G}^- example

Encoding of λ -terms

$$\lambda x. \lambda y. x y \rightsquigarrow \text{lam} (\lambda x. \text{lam} (\lambda y. \text{app} (\text{var } x) (\text{var } y)))$$

Type checking for λ -terms

$$tc\ G\ (\text{var } X)\ A \triangleq \text{lookup } X\ A\ G$$

$$tc\ G\ (\text{app } M\ N)\ B \triangleq \exists A. tc\ G\ M\ (\text{arr } A\ B) \wedge tc\ G\ N\ A$$

$$tc\ G\ (\text{lam } \lambda x. E\ x)\ (\text{arr } A\ B) \triangleq \nabla x. tc\ (\text{bind } x\ A\ G)\ (E\ x)\ B$$

\mathcal{G}^- basics

Syntax

$$t, u ::= x \mid c \mid a \mid (tu) \mid \lambda x.t$$

$$B, C ::= \top \mid p \vec{t} \mid t = u \mid B \wedge C \mid B \vee C \mid \exists x.B \mid \nabla z.B$$

$$D ::= \forall \vec{x}. [(\nabla \vec{z}. p \vec{u}) \triangleq B]$$

Notions

Equality is λ -conversion: $\lambda a.a = \lambda b.b$, $(\lambda x.t) u = t[u/x]$

Capture-avoiding substitution: $\exists X.\lambda a.X = \lambda b.b$ has no solution.

\mathcal{G}^- rules

$$\frac{}{\longrightarrow \top} \top \mathcal{R}$$

$$\frac{}{\longrightarrow t = t} = \mathcal{R}$$

$$\frac{\longrightarrow B_1 \quad \longrightarrow B_2}{\longrightarrow B_1 \wedge B_2} \wedge \mathcal{R}$$

$$\frac{\longrightarrow B_i}{\longrightarrow B_1 \vee B_2} \vee \mathcal{R}$$

$$\frac{\longrightarrow B[t/x]}{\longrightarrow \exists x.B} \exists \mathcal{R}$$

$$\frac{\longrightarrow B[a/x]}{\longrightarrow \nabla x.B} \nabla \mathcal{R}, \quad a \notin \text{supp}(B)$$

$$\frac{\longrightarrow B\theta}{\longrightarrow p \vec{t}} \vec{\text{def}} \mathcal{R}$$

Where $\forall \vec{x}. [(\nabla \vec{z}. p \vec{u}) \triangleq B] \in \mathcal{D}$ and θ is a substitution for \vec{z} and \vec{x} such that each $z_i\theta$ is a unique nominal constant, $\text{supp}(\vec{x}\theta) \cap \{\vec{z}\theta\} = \emptyset$, and $\vec{t} = \vec{u}\theta$.

A Naive Translation

$$\langle \cdot \rangle \cdot \rightsquigarrow \lambda \quad \forall \rightsquigarrow \nabla \quad \approx \rightsquigarrow =$$

Problem

$$\forall a. \exists X. \langle a \rangle X \approx \langle b \rangle b \rightsquigarrow \nabla a. \exists X. \lambda a. X = \lambda b. b$$

The first has solution $X \mapsto a$, the second has no solution

Solution

Use raising to explicitly encode dependencies:

$$\forall a. \exists X. \langle a \rangle X \approx \langle b \rangle b \rightsquigarrow \exists X. \lambda a. X a = \lambda b. b$$

Now the second formula has solution $X \mapsto \lambda y. y$

Freshness

There is no direct analog of $a\#t$ in \mathcal{G}^-

But we can define it:

$$\forall E. (\nabla x. \text{fresh } x \ E) \triangleq \top$$

x is quantified inside the scope of E so no substitution for E can contain the value of x

Translation for terms

$$\phi(a) = a \quad \phi(f(\vec{t})) = f \overrightarrow{\phi(t)} \quad \phi(\langle a \rangle t) = \lambda a. \phi(t)$$

$$\phi(X \vec{a}) = X \vec{a} \quad \phi((a b) \cdot t) = (a b) \cdot \phi(t)$$

Example

$lam(\langle a \rangle lam(\langle b \rangle app(X, (a b) \cdot X)))$

\rightsquigarrow

$lam(\lambda a. lam(\lambda b. app(X a b)(X b a)))$

Translation for goals and clauses

$$\phi_{\vec{a}}(\top) = \top$$

$$\phi_{\vec{a}}(p \vec{t}) = \nabla \vec{a}. p \overrightarrow{\phi(\vec{t})}$$

$$\phi_{\vec{a}}(a \# t) = \nabla \vec{a}. \text{fresh } \phi(a) \phi(t)$$

$$\phi_{\vec{a}}(t \approx u) = \nabla \vec{a}. (\phi(t) = \phi(u))$$

$$\phi_{\vec{a}}(G_1 \wedge G_2) = \phi_{\vec{a}}(G_1) \wedge \phi_{\vec{a}}(G_2)$$

$$\phi_{\vec{a}}(G_1 \vee G_2) = \phi_{\vec{a}}(G_1) \vee \phi_{\vec{a}}(G_2)$$

$$\phi_{\vec{a}}(\exists X. G) = \exists X. \phi_{\vec{a}}(G[X \vec{a}/X])$$

$$\phi_{\vec{a}}(\forall b. G) = \phi_{\vec{a}b}(G)$$

$$\phi(\forall \vec{a}. \forall \vec{X}. [p(\vec{t}) :- G]) = \forall \vec{X}. [(\nabla \vec{a}. p \overrightarrow{\phi(\vec{t}\sigma)}) \triangleq \phi_{\vec{a}}(G\sigma)]$$

$$\text{where } \sigma = \{X \vec{a}/X \mid X \in \vec{X}\}$$

Correctness of the translation

Theorem (Soundness)

If $\Delta \implies G$ then $\longrightarrow \phi(G)$ with the definitions $\phi(\Delta)$

Theorem (Completeness)

If $\longrightarrow \phi(G)$ with the definitions $\phi(\Delta)$ then $\Delta \implies G$

Type checking example

$tc(G, var(X), A) :- lookup(X, A, G)$

$tc(G, app(M, N), B) :- \exists A. tc(G, M, arr(A, B)) \wedge tc(G, N, A)$

$tc(G, lam(\langle x \rangle E), arr(A, B)) :- x \# G \wedge tc(bind(x, A, G), E, B)$

$tc\ G\ (var\ X)\ A \triangleq lookup\ X\ A\ G$

$tc\ G\ (app\ M\ N)\ B \triangleq \exists A. tc\ G\ M\ (arr\ A\ B) \wedge tc\ G\ N\ A$

$(\nabla x. tc\ (G\ x)\ (lam\ \lambda x. E\ x)\ (arr\ (A\ x)\ (B\ x))) \triangleq$

$(\nabla x. fresh\ x\ (G\ x)) \wedge$

$(\nabla x. tc\ (bind\ x\ (A\ x)\ (G\ x))\ (E\ x)\ (B\ x))$

Simplifications

$$\begin{aligned} & (\nabla x. tc (G x) (lam \lambda x. E x) (arr (A x) (B x))) \triangleq \\ & (\nabla x. fresh x (G x)) \wedge \\ & (\nabla x. tc (bind x (A x) (G x)) (E x) (B x)) \end{aligned}$$

1. Statically solve freshness constraint:

$$\begin{aligned} & (\nabla x. tc G (lam \lambda x. E x) (arr (A x) (B x))) \triangleq \\ & \nabla x. tc (bind x (A x) G) (E x) (B x) \end{aligned}$$

2. Use *subordination* to elimination vacuous raisings:

$$\begin{aligned} & (\nabla x. tc G (lam \lambda x. E x) (arr A B)) \triangleq \\ & \nabla x. tc (bind x A G) (E x) B \end{aligned}$$

3. Remove vacuous ∇ s:

$$tc G (lam \lambda x. E x) (arr A B) \triangleq \nabla x. tc (bind x A G) (E x) B$$

Extending the translation

α Prolog allows arbitrary abstraction and swapping:

$$\langle u \rangle t \qquad (u_1 u_2) \cdot t$$

$$\begin{aligned} t' \approx \langle u \rangle t &\rightsquigarrow \text{*abst* } u \ t \ t' \\ t' \approx (u_1 u_2) \cdot t &\rightsquigarrow \text{*swap* } u_1 \ u_2 \ t \ t' \end{aligned}$$

$$\forall E. (\nabla x. \text{*abst* } x \ (E \ x) \ (\lambda x. E \ x)) \triangleq \top$$

$$\forall E. (\nabla x, y. \text{*swap* } x \ y \ (E \ x \ y) \ (E \ y \ x)) \triangleq \top$$

$$\forall E. (\nabla x. \text{*swap* } x \ x \ (E \ x) \ (E \ x)) \triangleq \top$$

Going fully higher-order

Encoding of λ -terms

$$\lambda x. \lambda y. x y \rightsquigarrow \text{lam } \lambda x. \text{lam } \lambda y. \text{app } x y$$

Type checking for λ -terms in λ Prolog

$$tc (\text{app } M N) B :- tc M (\text{arr } A B) \wedge tc N A$$

$$tc (\text{lam } \lambda x. R x) (\text{arr } A B) :- \forall x. tc x A \Rightarrow tc (R x) B$$

Free lemma

If $\Delta \vdash tc (\text{lam } \lambda x. R x) (\text{arr } A B)$ and $\Delta \vdash tc N A$ then
 $\Delta \vdash tc (R N) B$

λ Prolog in \mathcal{G}^-

$$\text{seq } L \top \triangleq \top$$

$$\text{seq } L (B \wedge C) \triangleq \text{seq } L B \wedge \text{seq } L C$$

$$\text{seq } L (A \Rightarrow B) \triangleq \text{seq } (A :: L) B$$

$$\text{seq } L (\forall x. B x) \triangleq \nabla x. \text{seq } L (B x)$$

$$\text{seq } L \langle A \rangle \triangleq \text{member } A L$$

$$\text{seq } L \langle A \rangle \triangleq \exists B. \text{prog } A B \wedge \text{seq } L B$$

$$\text{prog } (tc \text{ (app } M N) B)$$

$$(\langle tc M \text{ (arr } A B) \rangle \wedge \langle tc N A \rangle) \triangleq \top$$

$$\text{prog } (tc \text{ (lam } \lambda x. R x) \text{ (arr } A B))$$

$$(\forall x. tc x A \Rightarrow \langle tc (R x) B \rangle) \triangleq \top$$

Future Work

- ▶ Reverse translation [Cheney 2005]
- ▶ Mixing \mathcal{G}^- and λ Prolog specifications
- ▶ Reasoning about α Prolog via \mathcal{G}
- ▶ Identifying special subclasses of α Prolog specifications
- ▶ Unification, specification, reasoning